

Thomson Warner Linear H-Track Electro-Hydraulic Linear Actuator

Installation Manual

Edition 2019-11



Version history

Edition	Reason for revision
2019-11	First edition

Warranty

The Thomson Warner Linear H-Track is warranted to be free from defects in materials and workmanship for a period of twelve (12) months from date of delivery. The application of this product is the responsibility of the buyer and Thomson makes no representation or warranty as to the suitability of the product for any particular use or purpose. For a copy of the entire warranty for this product that is contained in our standard terms and conditions of sale, please go to http://www.thomsonlinear.com/website/com/eng/support/terms_and_conditions.php.

Disclaimer

Technical changes to improve the performance of the equipment may be made without prior notice!

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1. General

1.1 About this manual

This manual contains mechanical and electrical installation instructions for the Thomson Warner Linear H-Track electro-hydraulic linear actuator. It also contains, among other things:

- technical data
- installation data
- type designation key.

It is important to carefully read this manual before installing the actuator and to have the correct qualifications needed to perform the installation.

1.2 Target group

This manual addresses qualified mechanical and electrical personnel.

1.3 Symbols used



This symbol is shown to highlight a general warning, general instruction or as a warning for a mechanical hazard.

1.4 Transport and storage

The actuator may only be transported and stored in the original packaging supplied by Thomson. The temperature during transportation and storage must be between -40 to +65° C (-40 to +150° F). Avoid shocks to the package. If the package is damaged, check the actuator for visible damage and notify the carrier, and if appropriate also Thomson.

1.5 Packaging

The packaging consists of a cardboard box. The box contains the actuator and this manual. For large quantity orders, bulk packaging may be used in which case the packaging and the content will vary depending on the order agreement.

1.6 Disposal

Where required by law, used packaging and actuators are taken back by Thomson for professional disposal if the transportation cost is paid by the sender. Please contact Thomson for shipping information.

1.7 Support

If technical support or information is needed for this product, please contact the nearest Thomson Service Center. See the back of this manual. You can also visit www.thomsonlinear.com for information on this product and how to contact us.

2. Safety

2.1 Safety notes



- Only properly qualified personnel are permitted to perform mechanical and electrical installation of this product. Properly qualified personnel are familiar with mechanical or electrical installation work and have the appropriate qualifications for their job.
- Read this manual and any other available documentation before working on the equipment that the actuator is or shall be a part of.
- Conform strictly to the information contained in this manual and on the actuator product label on the actuator. Never exceed the performance limits stated herein.
- Never work on the actuator or its installation with the power on.
- Never unplug any cables or connectors during operation or with power on.
- Immediately stop using the actuator if it seems faulty or damaged in any way and notify an appropriate person so that corrective actions can be taken.
- Never open the actuator as that will compromise the sealing, the function of the actuator and allow hydraulic fluid to escape. There are no serviceable components inside.
- Collaring of hydraulic fluid on the piston rod is normal. Over the life of the product, drops may accumulate. Hydraulic fluid film should not be removed.

3. Standards

3.1 EC Declaration of incorporation of partly completed machinery

We, Thomson Linear, declare that this product corresponds with the International Standard ISO 13766:2006-05 2nd Edition (Earth Moving Machinery, Electromagnetic Compatibility). The directive (MD) 2006/42/EC annex 2.1.B, RoHSII directive 2011/65/EU, and that the standard EN ISO 12100:2010, Safety of machinery, have been applied.

Thomson Warner Linear H-Track Actuator

Product

Hxx-xx-xxxx-x-xx

Description

Can be used when the machine or the system, which it shall be, a part of is in accordance with the demands in the EEC Machinery Directive and/or other relevant regulations.

08/06/2019

Date

Jared Zammuto

Name

NPDT Manager

Title

Signature

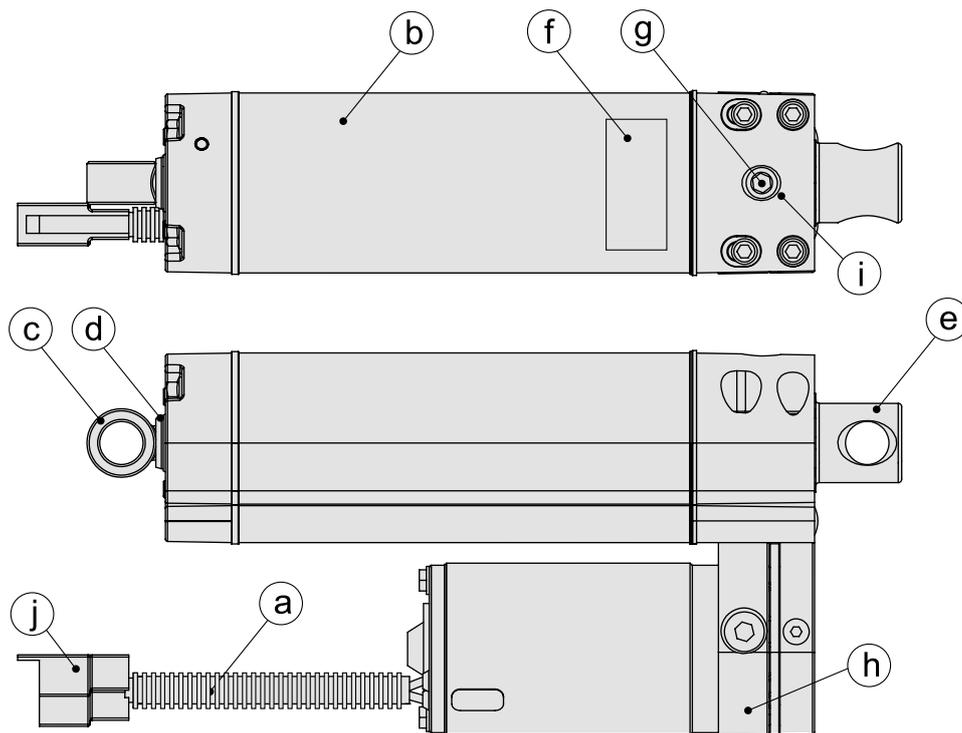
4. Installation

4.1 Product label

The product label can be found on the side of the reservoir tube. It will tell you which model of actuator you have, manufacturing date, country of origin; address of manufacturing location, phone contact number and traceable serial number with barcode. Please study the product label to determine actuator type before starting any installation or service on the actuator. If you need any assistance from Thomson, please provide the serial number, manufacturing date and the designation of the actuator(s) in question. You can also directly access H-Track information on www.thomsonlinear.com.



4.2 Terminology



- a. motor wires in loom
- b. reservoir tube (tank)
- c. rod end (standard shown)
- d. piston rod
- e. base end
- f. product label
- g. manual release input
- h. pump
- i. plug for manual release
- j. connector (shown) or ring terminals depending on motor model

4.3 Operation environment



Min. -40° C (-40° F)



Max. +65° C (+150° F)



IP66 / IP69K

1. Operation temperature range is -40 to +65° Celsius (-40 to +150° Fahrenheit).
2. Protection degree against the ingress of water and particles is IP66 / IP69K.
3. Relative humidity range is 10 - 90 % non-condensing.

4.4 Mechanical installation

4.4.1 General installation safety notes



- Never work on the actuator with the power switched on.
- Do not hold the piston while the unit is energized.
- Failure modes of the actuator should be considered to ensure it does not create harm.

4.4.2 Basic installation considerations

1. Only mount the actuator using the hole in the base end (section 4.2 (c)) and the rod end (e). The rod end can be one of four types - standard (hole), spherical joint, male thread or female thread.
2. Make sure that the actuator mounting position allows access to the motor wires (a), so that access is provided to connect/disconnect power.
3. The manual release (g) must have enough free space around it to allow it to be operated (section 4.4.6).
4. The rod end (c) must be locked with anaerobic adhesive to prevent it from unthreading.

4.4.3 Metering configuration installation considerations

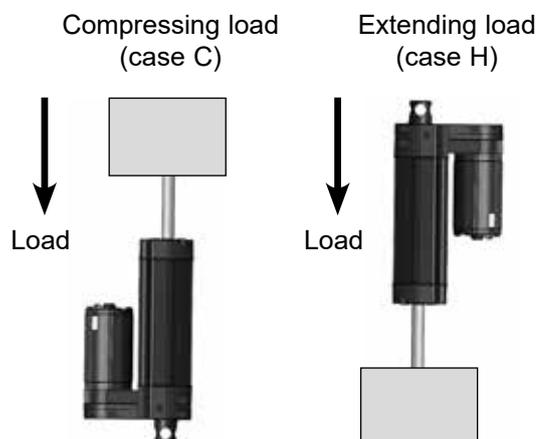
The metering configuration of an actuator is determined by studying the product label (section 4.1) and then looking the configuration up (C, H, B or N) in the ordering key (section 6.4). Make sure to install the actuator in accordance to its metering configuration limitations.

C = loads are only allowed to compress (push) the rod

H = loads are only allowed to extend (pull) the rod

B = loads are allowed to either compress and/or extend (pull or push) the rod

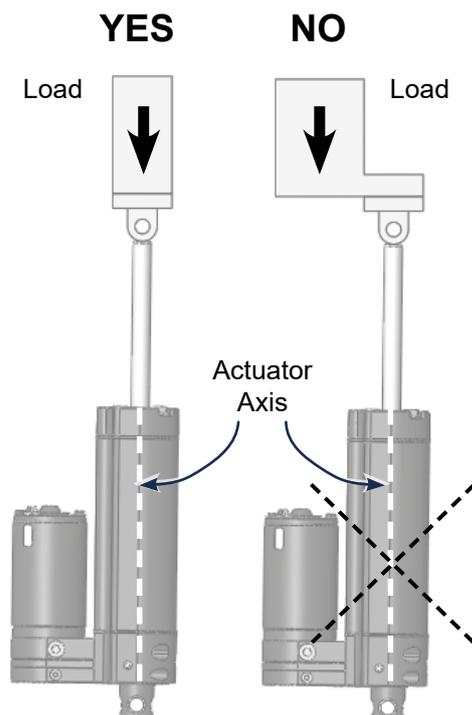
N = loads are not allowed to compress or extend (pull or push) the rod



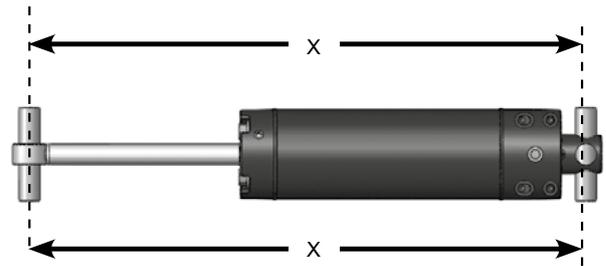
4.4.4 Mounting orientation and forces

Make sure the actuator metering configuration (section 4.4.3) is taken into consideration and that there is enough space between the rear base end and any surrounding objects to allow the manual release to be accessed (section 4.4.5), before moving onto the next steps.

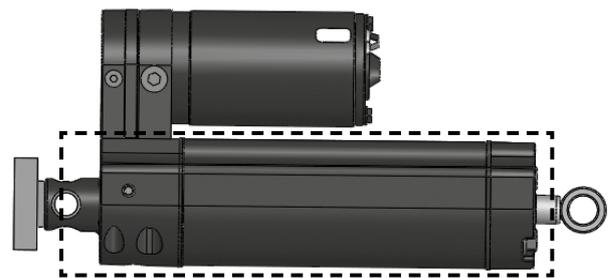
1. Only mount the actuator to the rear and front adapter mounting holes.
2. Always install actuator so that the force of the load acts in the center of the piston rod and the rear adapter (a).
3. Only use solid mounting pins and support them at both ends (b).
4. The mounting pins must be parallel to each other both radially and axially (c).
5. Do not attempt to mount the actuator at the tank tube (d).



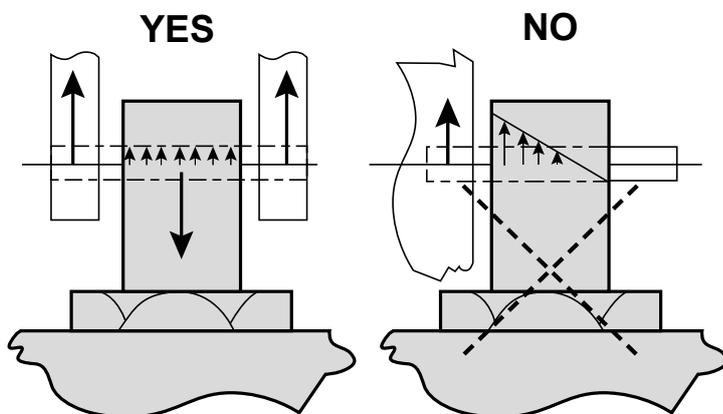
(a) Load must act in the piston rod center.



(c) Mounting pins must be parallel.



(d) Do not mount the actuator at the tank tube.



Mounting pins must be solid and supported at both ends (b).

4.4.5 Manual release and operation

1. To operate the manual release, isolate the load from the actuator so piston rod is unloaded with less than 3 mm (0.13 inch) of movement.
2. Use a flat-head screwdriver (a) to pierce a hole in the plug and pry cap free to get access to the manual release input (b).
3. Rotate manual release $\frac{1}{4}$ turn at a time counter-clockwise (left) using a $\frac{1}{4}$ inch hexagon key (c). Carefully observe the unit after each $\frac{1}{4}$ turn (left) for piston rod movement. Once the piston rod begins to move, wait for the actuator to be completely unloaded.
4. Once the unit is unloaded and the load is safe, the actuator can be removed from service.
5. Do not reinstall the actuator after engaging the manual release.



Never use any type of drill or power tool to operate the manual release.



(a) Flat-head screwdriver



(b) Manual release input



(c) $\frac{1}{4}$ inch hexagon key

4.5 Electrical installation and operation

4.5.1 General notes



- Make sure the leads leading to the motor can handle the maximum motor current.
- An emergency stop is recommended to reduce the chance of a crushing hazard.
- Never work on the actuator or the wiring with the power switched on.

4.5.2 Fuse size

Protect the actuator and the wiring by using a slow blow fuse between the actuator and the power source.

Recommended fuse size		
Actuator supply voltage	Fuse size	
	250 W motor	560 W motor
12 Vdc	50 A	100 A
24 Vdc	20 A	40 A

4.5.3 Motor wire connections

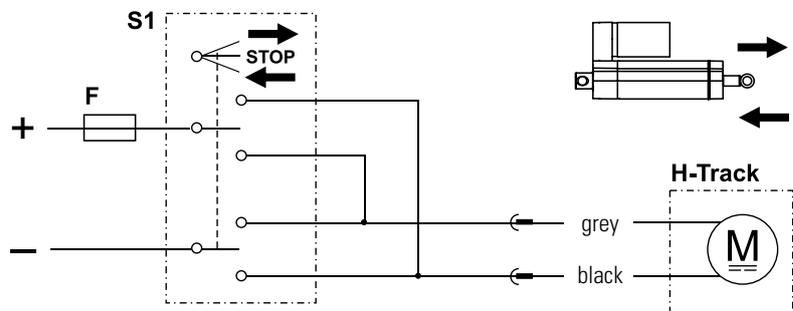
The actuator is always supplied with two power wires. In the end of the wires, there is a Packard 56 series connector body 2973781 with 2 female terminals 2962447 on the 250 W motor, while there are ¼ inch ring terminals on the 560 W motor.

4.5.4 Lead cross sections

To avoid malfunction due to voltage drop, the cross section of the leads between the actuator power cable leads and the power source must be of sufficient size. Calculations based on the supply voltage, the current draw, the length of the cables, the ambient temperature and the local regulations must be done.

4.5.5 Electrical connection

- F Fuse
- S1 Double pole double throw switch



To extend the actuator, apply +Vdc to black -Vdc to grey. To retract, apply -Vdc to black and +Vdc to grey. Avoid running the actuator in to the ends.



Always turn power off to the actuator before working on it.

4.5.6 Motor thermal switch

The motor is equipped with a bi-metal thermal switch, which will trip and stop the motor in case of overheating. The switch will reset automatically once the motor has cooled down. Always investigate and, if necessary, correct the cause(s) of a trip before taking the actuator into operation again.”

5. Troubleshooting

5.1 Troubleshooting

Troubleshooting list		
Issue	Problem	Solution
Actuator does not move, makes no sound.	Actuator is not receiving proper input voltage.	Ensure the actuator is being supplied with proper rated input voltage.
Actuator makes buzzing sound, does not move.	Actuator does not have enough power and is stalled.	Ensure your power supply can provide enough current to move the rated load.
Actuator moves slower/faster than expected.	Actuator is receiving too low/ too high input voltage.	Ensure that actuator is provided with proper nominal input voltage amount (i.e. 12 Vdc for a 12 Vdc rated actuator).
The actuator, when powered, is causing the fuse to blow.	Fuse is not rated for current draw of the actuator.	Make sure that the fuse is rated for the in-rush current of the actuator, which is typically 1.5 times the rated current draw of the actuator at full load. Slow-blow fuses are also recommended.
The actuator stops during motion but can, after a while, be operated again	The thermal switch in the motor has tripped due to an overload/overheating condition, disconnecting the actuator motor until the switch has cooled down and resets automatically.	Make sure the combination of load, duty cycle and/or ambient temperature is within the permissible limits and that there are no problems with any related mechanical linkage, forcing the actuator to work harder than expected. Possible solutions include reducing the load and/or duty cycle, lowering the ambient temperature and using forced cooling
The actuator is not stopping at the right place.	Actuator is coasting due to helping load/lack of dynamic braking.	Consider shorting the motor leads together when stopping the actuator to dynamically brake the motor, especially in circumstances where the load applied would "help" move the piston rod.
Actuator motor is spinning but piston rod is not moving.	The actuator has encountered impact load that has caused a vacuum imposed on the fluid and created air bubbles.	Allow actuator to rest in rod up position for air to migrate back to the reservoir. If actuator does not return to normal state, the actuator will need to be analyzed as an RMA (Return Material Authorization) at the manufacturing facility.
The actuator is leaking more than rod collaring.	The actuator has become damaged.	Actuator will need to be analyzed as an RMA (Return Material Authorization) at the manufacturing facility.
The actuator drifts over time exceeding 0.008 inch linear travel per hour.	The actuator relief valves are leaking. It is normal for the actuator to drift 0.008 inch linear travel per hour while loaded. Similar to a traditional hydraulic system.	Actuator will need to be analyzed as an RMA (Return Material Authorization) at the manufacturing facility.

6. Technical specifications

6.1 Technical data

Technical specification	H-Track	
Input voltages [Vdc]	12	24
Input voltage tolerance [Vdc]	9 - 16	18 - 32
Stroke length [in]	see model number on product label and consult ordering key	
Static load (Fx), ends of stroke, maximum ⁽¹⁾ [kN (lbs)]	44.5 (10 000)	
Static load (Fx), mid stroke, maximum ⁽¹⁾	1.25 × maximum dynamic load	
Dynamic load (Fx), maximum [lbs]	see model number on product label and consult ordering key	
Speed @t no load / max. load ⁽²⁾ [in/s]	see model number on product label, consult ordering key and appropriate load chart	
Current draw @ rated max. load [A]	see model number on product label, consult ordering key and the power supply chart	
Weight ⁽¹⁾ [lbs]	see table section 6.2	
End play, maximum [mm (in)]	0.4 (0.015)	
Operating temperature limits, standard units [°C (°F)]	- 40 to + 85 (- 40 to + 185)	
Full load duty cycle [%]	25	
Restraining torque [Nm (lbf-in)]	0.1 (0.89)	
Motor leads cross section [mm ² (AWG)]	250 W motor models 560 W motor models	
	2.0 (14) 3.0 (12)	
Motor leads length (depending on option) [mm (in)]	254 ± 25 (10 ± 1)	
Motor leads termination type 250 W motor models 560 W motor models	Packard 56 series connector ring terminals	
Protection class - static	IP67 / IP69K	
Protection class - dynamic	IP66	
Safety features Pressure relief valve extend Pressure relief valve retract Motor bi-metal thermal switch	yes yes yes	
Compliances	CE, RoHS, Prop65, Reach	

(1) When fully retracted/extended, the actuator can be subjected to an extending/compressing static load up to 44.5 kN (10 000 lbs). Loads acting in the opposite direction or anywhere near mid-stroke can only be 1.25 × maximum dynamic load before the actuator starts to drift.

(2) Speeds vary depending on load.

6.2 Weight

Weight [lbs] *								
Designation	Stroke							
	2	4	6	8	10	12	14	16
H1x-xx-1	6.4	7.2	8.0	8.8	9.6	10.4	11.2	12.0
H2x-xx-1	6.9	7.8	8.7	9.6	10.5	11.4	12.3	13.2
H3x-xx-1	7.1	8.2	9.3	10.4	11.5	12.6	13.7	14.8
H1x-xx-2	8.0	8.8	9.6	10.4	11.2	12.0	12.8	13.6
H2x-xx-2	8.5	9.4	10.3	11.2	12.1	13.0	13.9	14.8
H3x-xx-2	8.7	9.8	10.9	12.0	13.1	14.2	15.3	16.4

* Conversion factor for pound to kilogram: 1 lb = 0.4536 kg

6.3 Load and speed charts

7.3.1 Load and speed charts

Consult the product label for information on the actuator model number. Next consult the ordering key and look up the load and speed for your actuator in the appropriate load and speed chart below.

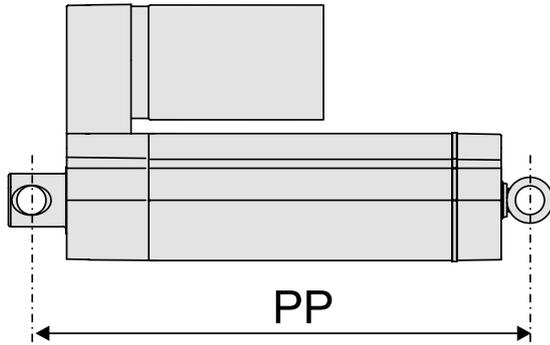
250 W motor performance							
Actuator configuration		Max. load [lbs]		Extension speed [in/s]		Retraction speed [in/s]	
Bore size code	Pump code	Extending	Retracting	No load	Max. load	No load	Max.load
H1	B4	500	375	3.5	1.0	4.38	1.25
H1	A4	750	563	2.0	0.6	2.50	0.75
H1	B1	1000	750	1.75	0.5	2.19	0.63
H2	B3	1250	992	1.4	0.4	1.69	0.48
H3	B3	1500	1125	1.2	0.35	1.50	0.44
H3	B2	1750	1313	1.0	0.29	1.25	0.36
H2	A2	2000	1587	0.65	0.19	0.78	0.23
H3	B1	2250	1688	0.8	0.23	1.00	0.29
H2	A1	2500	1983	0.5	0.15	0.60	0.18
H3	A1	3200	2400	0.45	0.13	0.56	0.16

560 W motor performance							
Actuator configuration		Max. load [lbs]		Extension speed [in/s]		Retraction speed [in/s]	
Bore size code	Pump code	Extending	Retracting	No load	Max. load	No load	Max.load
H1	B4	750	563	3.5	1.0	4.38	1.25
H1	A4	1125	844	2.0	0.6	2.50	0.75
H1	B1	1500	1125	1.75	0.5	2.19	0.63
H2	B3	1875	1488	1.4	0.4	1.69	0.48
H3	B3	2250	1688	1.2	0.35	1.50	0.44
H3	B2	2625	1969	1.0	0.29	1.25	0.36
H2	A2	3000	2380	0.65	0.19	0.78	0.23
H3	B1	3375	2531	0.8	0.23	1.00	0.29
H2	A1	3750	2975	0.5	0.15	0.60	0.18
H3	A1	4800	3600	0.45	0.13	0.56	0.16

6.4 Ordering key

Ordering key									
Position	1	2	3	4	5	6	7	8	9
Example	H2	C-	12-	1	A2	2-	A-	06	R90
<p>1. Bore size H1 = 1.000 H2 = 1.375 H3 = 1.500</p> <p>2. Metering configuration C- = meter out compression H- = meter out extension B- = meter out both N- = no meter out</p> <p>3. Supply voltage 12- = 12 Vdc 24- = 24 Vdc 48- = 48 Vdc</p> <p>4. Motor power 1 = 250 W 2 = 560 W</p> <p>5. Pump configuration A1 = (16 - 0.125) A2 = (16 - 0.156) A3 = (16 - 0.188) A4 = (16 - 0.250) B1 = (12 - 0.125) B2 = (12 - 0.156) B3 = (12 - 0.188) B4 = (12 - 0.250)</p>					<p>6. Rod diameter 1- = 0.500 inch rod (default for H1 bore size) 2- = 0.625 inch rod (default for H2 bore size) 3- = 0.750 inch rod (default for H3 bore size)</p> <p>7. Rod end option A = standard B = spherical C = male thread D = female thread</p> <p>8. Stroke length 02 = 2 inch (50 mm) 04 = 4 inch (100 mm) 06 = 6 inch (150 mm) 08 = 8 inch (200 mm) 10 = 10 inch (254 mm) 12 = 12 inch (300 mm) 14 = 14 inch (356 mm) 16 = 16 inch (406 mm)</p> <p>9. Mount Blank = standard R90 = 90° position</p>				

6.5 Base and rod end center to center distance



Base and rod end center to center distance at fully retracted (PP)																								
Bore/Rod	Rod End "A"						Rod End "B"						Rod End "C"						Rod End "D"					
	H1		H2		H3		H1		H2		H3		H1		H2		H3		H1		H2		H3	
	[in]	[mm]	[in]	[mm]	[in]	[mm]	[in]	[mm]	[in]	[mm]	[in]	[mm]	[in]	[mm]	[in]	[mm]	[in]	[mm]	[in]	[mm]	[in]	[mm]	[in]	[mm]
2 (50)	6.8	173	6.8	173	6.8	173	7.5	190	7.4	191	7.7	196	7.1	181	7.3	186	7.5	191	6.2	157	6.2	157	6.2	157
4 (100)	8.8	224	8.8	224	8.8	224	9.5	241	9.5	242	9.7	247	9.1	232	9.3	237	9.5	242	8.2	208	8.2	208	8.2	208
6 (150)	10.8	274	10.8	274	10.8	274	11.5	292	11.5	293	11.7	298	11.1	283	11.3	288	11.5	292	10.2	259	10.2	259	10.2	259
8 (200)	12.8	325	12.8	325	12.8	325	13.5	342	13.5	344	13.7	349	13.1	334	13.3	338	13.5	343	12.2	310	12.2	310	12.2	310
10 (254)	14.8	376	14.8	376	14.8	376	15.5	393	15.5	395	15.7	400	15.1	385	15.3	389	15.5	394	14.2	361	14.2	361	14.2	361
12 (300)	16.8	427	16.8	427	16.8	427	17.5	444	17.5	445	17.7	450	17.1	435	17.3	440	17.5	445	16.2	411	16.2	411	16.2	411
14 (350)	18.8	478	18.8	478	18.8	478	19.5	495	19.5	496	19.7	501	19.1	486	19.3	491	19.5	496	18.2	462	18.2	462	18.2	462
16 (400)	20.8	528	20.8	528	20.8	528	21.5	546	21.5	547	21.7	552	21.1	537	21.3	542	21.5	546	20.2	513	20.2	513	20.2	513

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